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What was the goal:

- To learn the basics about using the iCub
- To collect data using grasp reflex and swing motion useful later on for learning various motor primitives (hit, tap, grasp, carry etc.)

What I actually did:

- Implemented grasp reflex and tested on iCub
- Installed and run the Poeticon demo
- Attended lots of tutorials and talks
- Learned more about what others are doing in affordances and language

